



A Local Cauchy Integral Formula for Slice-Regular Functions

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Abstract

We prove a local Cauchy-type integral formula for slice-regular functions. The formula is obtained as a corollary of a general integral representation formula where the integration is performed on the boundary of an open subset of the quaternionic space, with no requirement of axial symmetry. As a step towards the proof, we provide a decomposition of a slice-regular function as a combination of two axially monogenic functions.

Keywords Slice-regular functions · Axially monogenic functions · Cauchy–Riemann operator · Cauchy integral formula

Mathematics Subject Classification 30G35 · 30E20 · 26B20

1 Introduction

Cauchy's integral formula is one of the most powerful tools in complex analysis. It plays a key role also in the study of any function theory that aims to extend complex analysis to higher dimensional algebras. In the four dimensional case represented by the quaternionic skew field, there are at least two different generalizations of the concept of holomorphic functions. Here we mention only the two function theories that will be used in the present paper. The first one deals with functions in the kernel of the Cauchy–Riemann–Fueter differential operator

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$$\overline{\partial} := \frac{1}{2} \left(\frac{\partial}{\partial x_0} + i \frac{\partial}{\partial x_1} + j \frac{\partial}{\partial x_2} + k \frac{\partial}{\partial x_3} \right),$$

where i, j, k are the quaternionic basic imaginary units and $x = x_0 + ix_1 + jx_2 + kx_3$ is the real representation of a quaternion x. These functions, usually called Fueter-regular or monogenic, have been studied extensively for many decades. Primary references are the article of Fueter [7], where Cauchy's integral theorem was proved, the paper of Sudbery [23] and the monograph [2], where the results were given in their generality in the context of Clifford analysis. The second function theory, introduced in 2006–2007 by Gentili and Struppa [10, 11] following an idea of Cullen [5], with the objective to include quaternionic polynomials and series, is the theory of quaternionic slice-regular functions. This function theory is based on the particular complex-slice structure of the quaternionic space \mathbb{H} . In Sect. 2 we briefly recall the definitions and properties of slice functions and slice-regular functions that are used in the subsequent sections.

A Cauchy-type integral formula for slice-regular functions was proved in the seminal paper [11]. A version of the Cauchy formula with slice-regular kernel was proved in [3]. In these formulas integration is performed over the boundary of a two-dimensional domain having an axial symmetry with respect to the real axis. A volume Cauchy-type formula, where integration is performed over the boundary of an open axially symmetric domain, was proved in [14] in the more general context of real alternative *-algebras. That result extended to every slice-regular function a similar one obtained by Cullen [5] on the quaternions. Further generalizations of the Cauchy formula were given in [13, 17].

The aim of the present paper is to prove a local Cauchy-type integral formula for slice-regular functions (Corollary 3). To achieve this goal near any point of the domain, not only for those on the real axis, it is necessary to have an integral representation formula where the integration is performed on the boundary of a not necessarily axially symmetric domain (Theorem 4). Observe that all the known Cauchy-type formulas in the literature of slice analysis require this symmetry condition. The integral kernel we construct is not slice-regular, but it is universal, i.e., not depending on the domain. An unavoidable aspect of the formula is the appearing, along with the boundary values of the slice-regular function, of the values of a complementary function, namely, the spherical derivative of a slice primitive of the function.

The Cauchy-type formula is proved using facts from both the above-mentioned quaternionic functions theories. We show (Theorem 3) that every slice-regular function can be expressed as a combination of two axially monogenic functions, to which the Fueter's version of Cauchy's integral formula apply. We recall that an axially monogenic function is a monogenic slice function, i.e., a slice function in the kernel of the operator $\overline{\partial}$. We also give a new proof (Theorem 2) of the surjectivity of the Laplacian mapping from the space of slice-regular functions to that of axially monogenic functions (see [4]). This result has a role in proving the uniqueness of the above-mentioned decomposition in terms of axially monogenic functions.



2 Preliminaries

The slice function theory of one quaternionic variable [10, 11] is based on the slice decomposition of the quaternionic space \mathbb{H} . For each element J in the sphere of quaternionic imaginary units

$$\mathbb{S} = \left\{ J \in \mathbb{H} \mid J^2 = -1 \right\} = \left\{ x_1 i + x_2 j + x_3 k \in \mathbb{H} \mid x_1^2 + x_2^2 + x_3^2 = 1 \right\},$$

we let $\mathbb{C}_J = \langle 1, J \rangle \simeq \mathbb{C}$ be the subalgebra generated by J. Then it holds

$$\mathbb{H} = \bigcup_{J \in \mathbb{S}} \mathbb{C}_J, \quad \text{with } \mathbb{C}_J \cap \mathbb{C}_K = \mathbb{R} \text{ for every } J, K \in \mathbb{S}, \ J \neq \pm K.$$

A differentiable function $f: \Omega \subseteq \mathbb{H} \to \mathbb{H}$ is called (*left*) *slice-regular* [11] on the open set Ω if, for each $J \in \mathbb{S}$, the restriction $f_{|\Omega \cap \mathbb{C}_J|}: \Omega \cap \mathbb{C}_J \to \mathbb{H}$ is holomorphic with respect to the complex structure defined by left multiplication by J. We refer the reader to [9] and the references therein for more results in this function theory.

Another approach to slice regularity was introduced in [12, 13] (see also [18] for recent developments), making use of the concept of *slice functions*. We briefly recall their definition and some operations on them. Given a set $D \subseteq \mathbb{C}$, invariant with respect to complex conjugation, a function $F: D \to \mathbb{H} \otimes \mathbb{C}$ that satisfies $F(\overline{z}) = \overline{F(z)}$ for every $z \in D$ (the conjugation in $\mathbb{H} \otimes \mathbb{C}$ is induced by complex conjugation in the second factor) is called a *stem function* on D, a concept already present in seminal works of Fueter [7] and Cullen [5].

Let $\Phi_J: \mathbb{C} \to \mathbb{C}_J$ be the canonical isomorphism that maps $a + \iota b \in \mathbb{C}$ to a + Jb (with $\iota^2 = -1$). Given an open set $D \subseteq \mathbb{C}$, let $\Omega_D = \bigcup_{J \in \mathbb{S}} \Phi_J(D) \subset \mathbb{H}$. Open sets in \mathbb{H} of the form $\Omega = \Omega_D$ are called *axially symmetric* sets. An axially symmetric connected set Ω is called a *slice domain* if $\Omega \cap \mathbb{R} \neq \emptyset$, a *product domain* if $\Omega \cap \mathbb{R} = \emptyset$. Any axially symmetric open set is a union of a family of domains of these two types.

The stem function $F = F_1 + \iota F_2$ on D (with $F_1, F_2 : D \to \mathbb{H}$) induces the *slice* function $f = \mathcal{I}(F) : \Omega_D \to \mathbb{H}$ as follows: if $x = \alpha + J\beta = \Phi_J(z) \in \Omega_D \cap \mathbb{C}_J$, then

$$f(x) = F_1(z) + JF_2(z)$$
.

The slice function f is called *slice-regular* if F is holomorphic w.r.t. the complex structure induced on $\mathbb{H} \otimes \mathbb{C}$ by the second factor. If a domain Ω in \mathbb{H} is axially symmetric and intersects the real axis, then this definition of slice regularity is equivalent to the one proposed by Gentili and Struppa [11]. We will denote by $\mathcal{SR}(\Omega)$ the right quaternionic module of slice-regular functions on Ω and by $\mathcal{S}^1(\Omega)$ the class of slice functions induced by stem functions of the class C^1 on Ω .

The *slice product* of two slice functions $f = \mathcal{I}(F)$, $g = \mathcal{I}(G)$ on $\Omega = \Omega_D$ is defined by means of the pointwise product of the stem functions:

$$f \cdot g = \mathcal{I}(FG)$$
.

The function $f = \mathcal{I}(F)$ is called *slice-preserving* if the \mathbb{H} -components F_1 and F_2 of the stem function F are real-valued. This is equivalent to the condition $f(\overline{x}) = \overline{f(x)}$ for every $x \in \Omega$. If f is slice-preserving, then $f \cdot g$ coincides with the pointwise product of f and g. If f, g are slice-regular on Ω , then also their slice product $f \cdot g$ is slice-regular on Ω .

The slice derivatives

$$\frac{\partial f}{\partial x}$$
, $\frac{\partial f}{\partial x^c}$

of a slice functions $f = \mathcal{I}(F)$ are defined by means of the Cauchy–Riemann operators applied to the inducing stem function F:

$$\frac{\partial f}{\partial x} = \mathcal{I}\left(\frac{\partial F}{\partial z}\right), \quad \frac{\partial f}{\partial x^c} = \mathcal{I}\left(\frac{\partial F}{\partial \overline{z}}\right).$$

It follows that f is slice-regular if and only if

$$\frac{\partial f}{\partial x^c} = 0$$

and if f is slice-regular on Ω then also $\frac{\partial f}{\partial x}$ is slice-regular on Ω . Moreover, the slice derivatives satisfy the Leibniz product rule w.r.t. the slice product. If $f = \frac{\partial g}{\partial x}$, we will say that g is a *slice primitive* of f.

We recall other two useful concepts introduced in [13]. Given a slice function $f = \mathcal{I}(F_1 + \iota F_2)$ on Ω , the function $f_s^{\circ} : \Omega \to \mathbb{H}$, called the *spherical value* of f, and the function $f_s' : \Omega \setminus \mathbb{R} \to \mathbb{H}$, called the *spherical derivative* of f, are defined as

$$f_s^{\circ}(x) := \frac{1}{2}(f(x) + f(\overline{x}))$$
 and $f_s'(x) := \frac{1}{2}\operatorname{Im}(x)^{-1}(f(x) - f(\overline{x})).$

The functions $f_s^{\circ} = \mathcal{I}(F_1)$ and $f_s' = \mathcal{I}(\beta^{-1}F_2)$ are slice functions, constant on 2-spheres $\mathbb{S}_x = \alpha + \mathbb{S}\beta$ for any $x = \alpha + J\beta \in \Omega \setminus \mathbb{R}$, and such that

$$f(x) = f_s^{\circ}(x) + \operatorname{Im}(x) f_s'(x) \tag{1}$$

for every $x \in \Omega \setminus \mathbb{R}$. The spherical derivative satisfies a Leibniz-type rule w.r.t. the slice product (see [13, §5]): $(f \cdot g)'_s = f'_s g^\circ_s + f^\circ_s g'_s$. For any slice-regular function f on Ω , f'_s extends as the slice derivative $\frac{\partial f}{\partial x}$ on $\Omega \cap \mathbb{R}$. Note that if f is slice-regular and $f'_s \equiv 0$, then $F_2 \equiv 0$ and F is locally constant. Another remarkable property of the spherical derivative of a slice-regular function is its harmonicity when considered as a map of four real variables (see Theorem 1 of Sect. 3).



3 An Axially Monogenic Decomposition for Slice-Regular Functions

Let $\overline{\partial}$ denote the Cauchy–Riemann–Fueter operator

$$\overline{\partial} = \frac{1}{2} \left(\frac{\partial}{\partial x_0} + i \frac{\partial}{\partial x_1} + j \frac{\partial}{\partial x_2} + k \frac{\partial}{\partial x_3} \right).$$

Given an axially symmetric domain Ω of \mathbb{H} , let $\mathcal{AM}(\Omega)$ be the class of axially monogenic functions, i.e., of monogenic slice functions on Ω :

$$\mathcal{AM}(\Omega) = \{ f \in \mathcal{S}^1(\Omega) \mid \overline{\partial} f = 0 \}.$$

There is a result, usually called Fueter's Theorem [7], which in its generalised form can be seen as a bridge between the class of slice-regular functions and the one of monogenic functions (see, e.g., [4]). We report this result from [21, Prop. 3.61, Cor. 3.6.2 and Thm. 3.6.3], where some formulas linking the spherical derivative of slice functions with the Cauchy–Riemann–Fueter operator were proved. Let Δ denote the Laplacian operator in \mathbb{R}^4 . In the statement of this result we will also need the global differential operator $\overline{\vartheta}$ introduced in [15]. For slice functions $f \in C^1(\Omega)$, $\overline{\vartheta} f = \frac{\partial f}{\partial x^c}$ on $\Omega \setminus \mathbb{R}$ (see [15, Thm. 2.2]).

Theorem 1 ([21]) Let Ω be an axially symmetric domain in \mathbb{H} . Let $f: \Omega \to \mathbb{H}$ be a slice function of class $C^1(\Omega)$. Then

- 1. $\overline{\partial} f = \overline{\partial} f f'_s = \frac{\partial f}{\partial x^c} f'_s$ on $\Omega \setminus \mathbb{R}$. In particular, f is slice-regular if and only if $\overline{\partial} f = -f'_s$, and f is axially monogenic if and only if $\frac{\partial f}{\partial x^c} = f'_s$.
- 2. If $f: \Omega \to \mathbb{H}$ is slice-regular, then:
 - (a) The four real components of f'_s are harmonic on Ω .
 - (b) The following generalization of Fueter's Theorem holds:

$$\overline{\partial} \Delta f = \Delta \overline{\partial} f = -\Delta f_{s}' = 0.$$

(c)
$$\Delta f = -4 \frac{\partial f_s'}{\partial x}$$
.

In the following we will also use the following result from [20], which shows that the Laplacian of a slice-regular function can be expressed by first order derivatives.

Lemma 1 ([20, Lem. 23]) If $f \in SR(\Omega)$, then for every $x \in \Omega$ we have

$$\operatorname{Im}(x)\Delta f = 2\left(f_s' - \frac{\partial f}{\partial x}\right) = -2\left(\overline{\partial}f + \frac{\partial f}{\partial x}\right).$$

It is known that the Laplacian (also called Fueter mapping in this context) maps the space $\mathcal{SR}(\Omega)$ onto $\mathcal{AM}(\Omega)$ surjectively (see [4, 6] and references therein). If Ω is connected, the inverse image in $\mathcal{SR}(\Omega)$ of a function $g \in \mathcal{AM}(\Omega)$ under Δ is unique up to a quaternionic affine function xa + b (see [20, Lem. 23(a)]). Using Lemma 1, we now give an elementary proof of the surjectivity of Δ under suitable topological hypotheses.



Theorem 2 Let $\Omega = \Omega_D$ be an axially symmetric open set in \mathbb{H} . Assume that every connected component of D is simply connected. Then the Laplacian

$$\Delta: \mathcal{SR}(\Omega) \to \mathcal{AM}(\Omega)$$

is surjective.

Proof Let $g = \mathcal{I}(G) = \mathcal{I}(G_1 + \iota G_2) \in \mathcal{AM}(\Omega)$. Let $\{e_0, e_1, e_2, e_3\}$ be a real basis of \mathbb{H} . The decomposition $G = \sum_{i=0}^3 G^i e_i$ defines four stem functions $G^i : D \to \mathbb{R} \otimes \mathbb{C} \simeq \mathbb{C}$. Let $G^i = G^i_1 + \iota G^i_2$, with G^i_1, G^i_2 real valued. Since $g \in \mathcal{AM}(\Omega)$, in view of Theorem 1 we have

$$\mathcal{I}\left(\frac{\partial G}{\partial \overline{z}}\right) = \frac{\partial g}{\partial x^c} = g'_s = \mathcal{I}(\beta^{-1}G_2),$$

i.e.,

$$\frac{\partial G}{\partial \overline{z}} = \beta^{-1} G_2.$$

Then

$$\frac{\partial G}{\partial \overline{z}} = \sum_{i=0}^{3} \frac{\partial G^{i}}{\partial \overline{z}} e_{i} = \beta^{-1} G_{2} = \sum_{i=0}^{3} (\beta^{-1} G_{2}^{i}) e_{i},$$

which implies

$$\frac{\partial G^i}{\partial \overline{z}} = \beta^{-1} G_2^i$$
 for each $i = 0, \dots, 3$.

Therefore $g = \sum_{i=0}^{3} g^{i} e_{i}$, with every $g^{i} = \mathcal{I}(G^{i}) \in \mathcal{AM}(\Omega)$ and slice-preserving. If we find $f^{i} \in \mathcal{SR}(\Omega)$ such that $\Delta(f^{i}) = g^{i}$, then $\Delta(\sum_{i=0}^{3} f^{i} e_{i}) = g$. We can then assume that $g \in \mathcal{AM}(\Omega)$ is slice-preserving, i.e., G_{1} and G_{2} are real valued.

Our aim is to find a slice-preserving $f \in \mathcal{SR}(\Omega)$ such that

$$\operatorname{Im}(x)g = 2\left(f_s' - \frac{\partial f}{\partial x}\right),\,$$

since then Lemma 1 gives $\Delta f = g$. As above, the condition $\overline{\partial}g = 0$ is equivalent to $\frac{\partial G}{\partial \overline{z}} = \beta^{-1}G_2$, i.e., if $z = \alpha + \iota\beta$,

$$\frac{\partial G_1}{\partial \alpha} - \frac{\partial G_2}{\partial \beta} = 2\beta^{-1}G_2, \quad \frac{\partial G_1}{\partial \beta} + \frac{\partial G_2}{\partial \alpha} = 0.$$
 (2)

Since any axially symmetric open set is a union of a family of slice domains or product domains, we can assume that Ω is a domain of one of these types.



If $\Omega = \Omega_D$ is a slice domain, D is a simply connected subset of \mathbb{C} . From the second equality in (2), we can find $H \in C^{\infty}(D, \mathbb{R})$ such that

$$4\frac{\partial H}{\partial \overline{z}} = 2\left(\frac{\partial H}{\partial \alpha} + i\frac{\partial H}{\partial \beta}\right) = -\overline{G} = -G_1 + iG_2.$$

Let

$$F_2(z) := \frac{\beta}{2}(H(z) + H(\overline{z})) \in C^{\infty}(D, \mathbb{R}).$$

Then F_2 is odd w.r.t. β , and we have

$$4\frac{\partial}{\partial \overline{z}}\left(\frac{F_2}{\beta}\right) = -\overline{G}.$$

A direct computation shows that

$$\Delta F_2 = G_2 - \frac{\beta}{2} \left(\frac{\partial G_1}{\partial \alpha} - \frac{\partial G_2}{\partial \beta} \right).$$

The first equality in (2) then implies that F_2 is harmonic on D. Let $F_1 \in C^{\infty}(D, \mathbb{R})$ be a harmonic conjugate of F_2 . Replacing F_1 with $(F_1(z) + F_1(\overline{z}))/2$ if necessary, we get that F_1 is even w.r.t. β and that $F := F_1 + \iota F_2$ is holomorphic on D, i.e., F is a stem function on D, inducing a slice-regular $f := \mathcal{I}(F)$ on Ω . It remains to show that

$$2\left(f_s' - \frac{\partial f}{\partial x}\right) = \operatorname{Im}(x)g,$$

or, equivalently, that

$$4\left(\frac{F_2}{\beta} - \frac{\partial F}{\partial z}\right) = (z - \overline{z})G.$$

We have

$$-\overline{G} = 4\frac{\partial}{\partial \overline{z}} \left(\frac{F_2}{\beta} \right) = \frac{4}{\beta} \frac{\partial F_2}{\partial \overline{z}} + \frac{2F_2}{\iota \beta^2} \quad \Rightarrow \quad -G = \frac{4}{\beta} \frac{\partial F_2}{\partial z} - \frac{2F_2}{\iota \beta^2}.$$

Then

$$4\left(\frac{F_2}{\beta} - \frac{\partial F}{\partial z}\right) = 4\frac{F_2}{\beta} - 2\iota\left(4\frac{\partial F_2}{\partial z}\right) = 4\frac{F_2}{\beta} - 2\iota\left(-\beta G + \frac{2F_2}{\iota\beta}\right) = 2\iota\beta G.$$

If $\Omega = \Omega_D$ is a product domain, let $D^+ = D \cap \mathbb{C}^+$ and $D^- = D \cap \mathbb{C}^-$. Since D^+ is simply connected, there exist $H \in C^{\infty}(D^+, \mathbb{R})$ such that $4\frac{\partial H}{\partial \overline{z}} = -\overline{G}$ on D^+ .



H can be extended to D setting $H(z) = H(\overline{z})$ for $z \in D^-$. Then as in the previous case $F_2 := \beta H$ is harmonic on D, odd w.r.t. β . Let $F_1 \in C^{\infty}(D^+, \mathbb{R})$ such that $F = F_1 + \iota F_2$ is holomorphic on D^+ . Setting $F_1(z) = F_1(\overline{z})$ for $z \in D^-$, F can be extended to a holomorphic stem function on D satisfying as above

$$4\left(\frac{F_2}{\beta} - \frac{\partial F}{\partial z}\right) = (z - \overline{z})G \quad \text{on } D.$$

In view of Theorem 1(2c), a right inverse $\widetilde{\Delta}: \mathcal{AM}(\Omega) \to \mathcal{SR}(\Omega)$ of Δ can be defined on axially monogenic polynomials as in [20, Prop. 24]. For every $n \in \mathbb{Z}$ it associates the slice-regular monomial $-\frac{1}{4}x^{n+2}$ to the rational function \mathcal{P}_n , defined by

$$\mathcal{P}_n(x) := -\frac{1}{4}\Delta(x^{n+2}) = \frac{\partial}{\partial x}((x^{n+2})_s').$$
(3)

The functions \mathcal{P}_n are axially monogenic and then harmonic. They are slice-preserving functions (not slice-regular for $n \neq 0$) on \mathbb{H} . They were computed already by Fueter in [7] (see formula (12) on p. 316) and afterwords used by many authors. For $n \geq 0$ the functions \mathcal{P}_n are polynomials of degree n in x_0, x_1, x_2, x_3 . For n < 0 they are homogeneous functions on $\mathbb{H} \setminus \{0\}$, still of degree n. The functions \mathcal{P}_n and \mathcal{P}_{-n} are related through the Kelvin transform of \mathbb{R}^4 ([21, Prop. 6.7(c)]). In particular, $\mathcal{P}_{-1} = \mathcal{P}_{-2} \equiv 0$, while $\mathcal{P}_{-3}(x) = \overline{x}/|x|^4$ is equal, up to a multiplicative constant, to the Cauchy–Fueter kernel

$$E(x) = \frac{1}{2\pi^2} \frac{\overline{x}}{|x|^4}$$

(see [7] and also [23], [19, Ch. 3] for more recent expositions).

For $n \ge 0$, the polynomials \mathcal{P}_n are related to the spherical derivatives $\widetilde{\mathcal{Z}}_n(x) := (x^{n+1})'_s$ of quaternionic powers. These functions are harmonic homogeneous polynomials of degree n in the four real variables x_0, x_1, x_2, x_3 . The polynomials $\widetilde{\mathcal{Z}}_n$ are called *zonal harmonic polynomials with pole 1*, since they have an axial symmetry with respect to the real axis (see [1, Ch. 5] and [21, 22]).

We are now able to write a decomposition of quaternionic polynomials in terms of a pair of axially monogenic polynomials.

Proposition 1 *For every* $n \in \mathbb{N}$ *, we have*

$$(n+1)x^n = \mathcal{P}_n(x) - \overline{x}\,\mathcal{P}_{n-1}(x) \tag{4}$$

for every $x \in \mathbb{H}$.

Proof It was proved in [21, Cor. 6.7] that for every $n \in \mathbb{N}$, the following holds

$$x^{n+1} = \widetilde{\mathcal{Z}}_{n+1}(x) - \overline{x} \, \widetilde{\mathcal{Z}}_n(x) = \widetilde{\mathcal{Z}}_{n+1}(x) - \overline{x} \cdot \widetilde{\mathcal{Z}}_n(x) \quad \text{for all } x \in \mathbb{H}.$$



Here the pointwise and slice products coincide since \overline{x} is a slice-preserving function. Taking slice derivatives and using the Leibniz property, we get

$$(n+1)x^{n} = \frac{\partial \widetilde{Z}_{n+1}(x)}{\partial x} - \overline{x} \cdot \frac{\partial \widetilde{Z}_{n}(x)}{\partial x} = \mathcal{P}_{n}(x) - \overline{x} \cdot \mathcal{P}_{n-1}(x) = \mathcal{P}_{n}(x) - \overline{x} \, \mathcal{P}_{n-1}(x).$$

Corollary 1 Let $P \in \mathbb{H}[X]$ have degree $d \geq 1$. There exist two axially monogenic polynomials Q_1 , Q_2 , of degrees d and d-1 respectively, such that

$$P(x) = Q_1(x) - \overline{x}Q_2(x)$$
 for all $x \in \mathbb{H}$.

Proof Let $P(x) = \sum_{n=0}^{d} x^n a_n$. The corollary follows immediately from Proposition 1 by setting

$$Q_1(x) = \sum_{n=0}^d \frac{\mathcal{P}_n(x)}{n+1} a_n$$
 and $Q_2(x) = \sum_{n=1}^d \frac{\mathcal{P}_{n-1}(x)}{n+1} a_n$.

Corollary 1 can be generalized to every slice-regular function. Before doing this, we show one more general property of axially monogenic functions.

Lemma 2 Let Ω be as in Theorem 2. If both g and $\overline{x}g$ are axially monogenic on Ω , then g is identically zero.

Proof Let \mathcal{D} be the first order linear operator defined for any slice function h of class $C^2(\Omega)$ by

$$\mathcal{D}(h) = \overline{\partial} \left(\overline{x} \frac{\partial h}{\partial x} \right). \tag{5}$$

We claim that if $f \in \mathcal{SR}(\Omega)$, then

$$\mathcal{D}(f_s') = \left(\frac{\partial f}{\partial x}\right)_s'.$$

Indeed, we have

$$\overline{x} \frac{\partial f_s'}{\partial x} = \frac{\partial (\overline{x} f_s')}{\partial x} = \frac{\partial (x_0 f_s' - \operatorname{Im}(x) f_s')}{\partial x} = \frac{\partial (x_0 f_s' + f_s^{\circ})}{\partial x} + \frac{\partial (-f_s^{\circ} - \operatorname{Im}(x) f_s')}{\partial x}$$
$$= \frac{\partial ((x f)_s')}{\partial x} - \frac{\partial f}{\partial x} = -\frac{1}{4} \Delta (x f) - \frac{\partial f}{\partial x},$$



where we used Theorem 1(2c). Then

$$\mathcal{D}(f_s') = -\frac{1}{4}\overline{\partial}\left(\Delta(xf)\right) - \overline{\partial}\left(\frac{\partial f}{\partial x}\right) = -\overline{\partial}\left(\frac{\partial f}{\partial x}\right) = \left(\frac{\partial f}{\partial x}\right)_s'$$

thanks to point (2b) of Theorem 1 applied to the slice-regular function xf and point (1) of the same theorem applied to $\frac{\partial f}{\partial x}$.

If $g \in \mathcal{AM}(\Omega)$, thanks to the surjectivity of $\Delta : \mathcal{SR}(\Omega) \to \mathcal{AM}(\Omega)$ we can assume that $g = \Delta f$, with $f \in \mathcal{SR}(\Omega)$. If also $\overline{x}g \in \mathcal{AM}(\Omega)$, then

$$0 = \overline{\partial}(\overline{x}g) = \overline{\partial}(\overline{x}\Delta f) = -4\overline{\partial}\left(\overline{x}\frac{\partial f_s'}{\partial x}\right) = -4\mathcal{D}(f_s') = -4\left(\frac{\partial f}{\partial x}\right)_s'.$$

Therefore $\frac{\partial f}{\partial x}$ is locally constant, f is (locally) an affine function f(x) = xa + b, with $a, b \in \mathbb{H}$ and $g = \Delta f = 0$.

Remark 1 Let \mathcal{D} be the operator defined in (5). The claim given in the proof of Lemma 2 shows that

$$\mathcal{D}(\widetilde{\mathcal{Z}}_{n+1}) = (n+2)\widetilde{\mathcal{Z}}_n$$
, i.e., $\overline{\partial}(\overline{x}\mathcal{P}_n) = (n+2)\widetilde{\mathcal{Z}}_n$

for every $n \in \mathbb{N}$.

Now we extend Corollary 1 to every slice-regular function. Since every monogenic function is harmonic, the result we obtain can be seen as a refinement of the Almansi type decomposition proved in [22, Thm. 4]

Theorem 3 Let f be slice-regular on an axially symmetric open set Ω . Assume that $\Omega = \Omega_D$, and that every connected component of D is simply connected. Then there exist two uniquely determined axially monogenic functions g_1 and g_2 , such that

$$f(x) = g_1(x) - \overline{x}g_2(x) \quad \forall x \in \Omega.$$

The functions g_1 and g_2 can be computed from a slice-regular primitive of f. If $f = \frac{\partial g}{\partial x}$ on Ω , with $g \in SR(\Omega)$, then

$$g_1 = -\frac{1}{4}\Delta(xg), \quad g_2 = -\frac{1}{4}\Delta g.$$

Moreover, f is slice-preserving if and only if g_1 and g_2 are slice-preserving.

Proof Since any axially symmetric open set is a union of a family of slice domains or product domains, we can assume that Ω is a domain of one of these types. Assume that there exists $g \in \mathcal{SR}(\Omega)$ such that $f = \frac{\partial g}{\partial x}$ on Ω . Then, using Theorem 1(2c), the Leibniz-type formula for spherical derivative (see [13, §5]) and (1) we get

$$-\frac{1}{4}\left(\Delta(xg) - \overline{x}\Delta g\right) = \frac{\partial((xg)_s')}{\partial x} - \overline{x}\frac{\partial(g_s')}{\partial x} = \frac{\partial}{\partial x}\left(x_0g_s' + g_s^\circ\right) - \overline{x}\frac{\partial(g_s')}{\partial x}$$



$$= \frac{\partial}{\partial x} \left(x_0 g_s' + g_s^{\circ} - \overline{x} g_s' \right) = \frac{\partial}{\partial x} \left(g_s^{\circ} + \operatorname{Im}(x) g_s' \right) = \frac{\partial g}{\partial x} = f.$$

The functions $g_1 := -\frac{1}{4}\Delta(xg)$ and $g_2 = -\frac{1}{4}\Delta g$ are axially monogenic on Ω thanks to Fueter's Theorem 1(2b). To conclude the existence part of the proof it remains to show that there exists a slice-regular primitive of f on Ω . Let $\{e_0, e_1, e_2, e_3\}$ be a real basis of \mathbb{H} . If $f = \mathcal{I}(F)$, the decomposition $F = \sum_{i=0}^3 F^i e_i$ defines four holomorphic stem functions $F^i: D \to \mathbb{R} \otimes \mathbb{C} \simeq \mathbb{C}$.

If $\Omega = \Omega_D$ is a slice domain, by assumption D is a simply connected subset of \mathbb{C} . Let $G^i: D \to \mathbb{C}$ be a holomorphic primitive of F^i , for i=0,1,2,3 and let \tilde{G}^i be defined on D by

$$\tilde{G}^{i}(z) := \frac{1}{2} (G^{i}(z) + \overline{G^{i}(\overline{z})}).$$

Then \tilde{G}^i is a holomorphic stem function on D such that $\frac{\partial \tilde{G}^i}{\partial z} = F^i$. The slice function $g = \mathcal{I}(\sum_{i=0}^3 \tilde{G}^i e_i)$ is a slice-regular primitive of f.

If $\Omega = \Omega_D$ is a product domain, let $D^+ = D \cap \mathbb{C}^+$. Since D^+ is simply connected, there exist holomorphic primitives $G^i_+:D^+\to\mathbb{C}$ of F^i , for i=0,1,2,3. Define G^i_- on $D^-:=D\cap\mathbb{C}^-$ by $G^i_-(z):=\overline{G^i_+(\overline{z})}$. Then the function G^i defined as G^i_+ on D^+ and as G^i_- on D^- is a holomorphic stem function on D such that $\frac{\partial G^i}{\partial z}=F^i$. We conclude by observing that the sum $\sum_{i=0}^3 G^i e_i$ induces a slice-regular primitive of f.

To prove uniqueness of g_1 , g_2 , we use the linearity of the mapping $(g_1, g_2) \mapsto f$ and Lemma 2. If $f \equiv 0$, then $0 \equiv g_1 - \overline{x}g_2$. This means that g_2 and $\overline{x}g_2 = g_1$ are axially monogenic, and then g_2 (and also g_1) is identically zero.

The last statement is immediate from the uniqueness of g_1 and g_2 . If f is slice-preserving, then also g and then Δg and $\Delta(xg)$ are slice-preserving. Conversely, if g_1 , g_2 are slice-preserving, then $g_1 - \overline{x}g_2$ has the same property.

Corollary 2 Formula (4) holds also for negative integers n and $x \in \mathbb{H} \setminus \{0\}$.

Proof If n=-1, both sides of formula (4) vanish. Let $n\in\mathbb{Z}, n\leq -2$. Since $(n+1)^{-1}x^{n+1}$ is a slice-regular primitive of x^n on $\mathbb{H}\setminus\{0\}$, Theorem 3 gives the monogenic decomposition

$$x^{n} = -\frac{1}{4}\Delta((n+1)^{-1}x^{n+2}) - \overline{x}\left(-\frac{1}{4}\Delta((n+1)^{-1}x^{n+1})\right)$$

Therefore

$$(n+1)x^n = -\frac{1}{4}\Delta(x^{n+2}) - \overline{x}\left(-\frac{1}{4}\Delta(x^{n+1})\right) = \mathcal{P}_n(x) - \overline{x}\mathcal{P}_{n-1}(x).$$



Example 1 Let $f(x) = \exp(x) \in \mathcal{SR}(\mathbb{H})$. Then

$$\exp(x) = -\frac{1}{4}\Delta(x\exp(x)) - \overline{x}\left(-\frac{1}{4}\Delta\exp(x)\right),\,$$

with $\Delta(x \exp(x))$ and $\Delta \exp(x)$ axially monogenic on \mathbb{H} . The function

$$\Delta \exp(x) = -2e^{x_0} \left(\operatorname{sinc}(\beta) - I_x (\operatorname{sinc}(\beta))' \right),$$

where

$$I_x = \frac{\operatorname{Im}(x)}{|\operatorname{Im}(x)|}, \quad \beta = |\operatorname{Im}(x)|,$$

coincides up to a multiplicative constant with the function $EXP_3(x)$ defined in [19, Ex. 11.34] in the more general context of Clifford algebras.

The function $\text{Log}(x) \in \mathcal{SR}(\mathbb{H} \setminus \{x \in \mathbb{R} \mid x \leq 0\})$ induced by the complex principal logarithm (see e.g. [22, Ex. 5]) is a slice-regular primitive of x^{-1} on $\mathbb{H} \setminus \{x \in \mathbb{R} \mid x \leq 0\}$. Then we can write

$$x^{-1} = -\frac{1}{4}\Delta(x\operatorname{Log}(x)) + \frac{\overline{x}}{4}\Delta(\operatorname{Log}(x)),$$

with $\Delta(x \operatorname{Log}(x))$ and $\Delta(\operatorname{Log}(x))$ axially monogenic on $\mathbb{H} \setminus \{x \in \mathbb{R} \mid x \leq 0\}$. The function $\Delta(\operatorname{Log}(x))$ coincides up to a multiplicative constant with the ∂ -primitive L(x) of the Cauchy–Fueter kernel E(x) defined in [23, (5.7)]. Here ∂ is the conjugated Cauchy–Riemann–Fueter operator.

The statement of Theorem 3 has a converse. In the following proposition we give a differential condition on the pair (g_1, g_2) that ensures the slice-regularity of $g_1 - \overline{x}g_2$.

Proposition 2 Let g_1 and g_2 be two axially monogenic functions on an axially symmetric set Ω . If f is defined as $f(x) = g_1(x) - \overline{x}g_2(x)$ for every $x \in \Omega$, then f is slice-regular on Ω if and only if

$$\frac{\partial g_1}{\partial x^c} = g_2 + \overline{x} \frac{\partial g_2}{\partial x^c}.$$
 (6)

Proof Clearly f is a slice function on Ω . From Theorem 1(1), f is slice-regular if and only if $f'_s = -\overline{\partial} f$. But $f'_s = (g_1)'_s - (\overline{x}g_2)'_s$, while

$$-\overline{\partial}f = \overline{\partial}(\overline{x}g_2) = \frac{\partial(\overline{x}g_2)}{\partial x^c} - (\overline{x}g_2)'_s = g_2 + \overline{x}\frac{\partial g_2}{\partial x^c} - (\overline{x}g_2)'_s.$$

Since again from Theorem 1(1) we have

$$(g_1)_s' = \frac{\partial g_1}{\partial x^c},$$

it follows that f is slice-regular if and only if (6) holds.



4 A Local Cauchy-Type Integral Formula

Let $\Omega = \Omega_D$ be an axially symmetric open set. Assume that every connected component of D is simply connected. Given $f \in \mathcal{SR}(\Omega)$, we know from the proof of Theorem 3 that it is possible to find a slice-regular primitive $g \in \mathcal{SR}(\Omega)$. Let $\mathcal{ZH}(\Omega)$ denote the right \mathbb{H} -module of *zonal harmonic functions with pole 1* on Ω , i.e., the quaternionic harmonic functions h on Ω , such that $h \circ T = h$ for every orthogonal transformation T of $\mathbb{H} \simeq \mathbb{R}^4$ that fixes 1.

Let Ω be a slice domain. Using Theorem 1(2a), we can define a linear operator

$$S: \mathcal{SR}(\Omega) \to \mathcal{ZH}(\Omega)$$

that maps f to the spherical derivative $g'_s = -\overline{\partial}g$ of any slice-regular primitive g of f. This map is well-defined since if

$$\frac{\partial g}{\partial x} = \frac{\partial \tilde{g}}{\partial x},$$

with g, \tilde{g} slice-regular, then $g - \tilde{g}$ is locally constant, and then $g'_s - \tilde{g}'_s = \overline{\partial}(\tilde{g} - g) = 0$. We have S(a) = a for any constant $a \in \mathbb{H}$, $S(x^n) = (n+1)^{-1} \tilde{Z}_n$ for every $n \in \mathbb{N}$ and $Sf(x) = f(x) \ \forall x \in \mathbb{R} \cap \Omega$. If f is slice-preserving, then Sf is real-valued. Moreover, S is injective, since

$$\ker(\mathcal{S}) = \left\{ f \in \mathcal{SR}(\Omega) \mid f = \frac{\partial g}{\partial x}, g \in \mathcal{SR}(\Omega) \cap \mathcal{AM}(\Omega) \right\} = \{0\}.$$

If Ω is a product domain, we define $\mathcal{S}(f)$ as the spherical derivative of any slice-regular primitive of f. Let

$$E(x) = \frac{1}{2\pi^2} \overline{x}/|x|^4 \in \mathcal{AM}(\mathbb{H} \setminus \{0\})$$

be the Cauchy–Fueter kernel and let Dy be the 3-form with quaternionic coefficients defined as in [23, (2.28)]:

$$Dy = dy_1 \wedge dy_2 \wedge dy_3 - idy_0 \wedge dy_2 \wedge dy_3 + jdy_0 \wedge dy_1 \wedge dy_3 - kdy_0 \wedge dy_1 \wedge dy_2,$$

where $y = y_0 + iy_1 + jy_2 + ky_3 \in \mathbb{H}$ with y_0, y_1, y_2, y_3 real. For every $x \in \mathbb{H}$, $y \in \mathbb{H} \setminus \mathbb{R}$, with $x \neq y$, define the two quaternionic 3-forms

$$K_1(x, y) := (E(y - x)(Dy)y - \overline{x}E(y - x)Dy)(y - \overline{y})^{-1},$$

$$K_2(x, y) := (\overline{x}E(y - x)Dy - E(y - x)(Dy)\overline{y})(y - \overline{y})^{-1}.$$

We are now in a position to prove a Cauchy-type integral formula for slice-regular functions on Ω where the integration is performed on the boundary of a not necessarily



axially symmetric open subset of Ω . As a consequence, we are able to prove a local Cauchy-type integral formula for slice-regular functions.

Theorem 4 Let f be slice-regular on an axially symmetric open set Ω . Assume that $\Omega = \Omega_D$, and that every connected component of D is simply connected. Let $U \subset \mathbb{H}$ be a bounded open set with rectifiable boundary and such that $\overline{U} \subset \Omega$. Then

$$f(x) = \int_{\partial U} \left(K_1(x, y) f(y) + K_2(x, y) \mathcal{S} f(y) \right) \tag{7}$$

for every $x \in U$.

Proof From Theorem 3 we get the decomposition $f(x) = g_1(x) - \overline{x}g_2(x)$ with axially monogenic components

$$g_1 = -\frac{1}{4}\Delta(xg), \qquad g_2 = -\frac{1}{4}\Delta g,$$

where $g \in \mathcal{SR}(\Omega)$ satisfies $\frac{\partial g}{\partial x} = f$. From the Cauchy–Fueter integral formula for monogenic, i.e., Fueter-regular, functions (see [7] for the original proof and also [23], where the formula was proved in its full generality), we get

$$f(x) = \int_{\partial U} E(y - x)(Dy)g_1(y) - \overline{x} \int_{\partial U} E(y - x)(Dy)g_2(y)$$

for every $x \in U$. Now we transform the two integrals using Lemma 1. We obtain

$$g_1 = (2\operatorname{Im}(x))^{-1} \left(-(xg)_s' + \frac{\partial (xg)}{\partial x} \right) = (2\operatorname{Im}(x))^{-1} \left(-\overline{x}g_s' + xf \right),$$
 (8)

where we used the equality

$$(xg)'_{s} = g_{s}^{\circ} + x_{0}g'_{s} = (g_{s}^{\circ} + \operatorname{Im}(x)g'_{s}) + \overline{x}g'_{s} = g + \overline{x}g'_{s},$$

and

$$g_2 = (2\operatorname{Im}(x))^{-1}(-g_s' + f).$$
 (9)

Using (8), (9) and $g'_s = \mathcal{S}\{$, we get

$$E(y - x)(Dy)g_1(y) - \overline{x}E(y - x)(Dy)g_2(y)$$

$$= \left(E(y - x)(Dy)(2\operatorname{Im}(y))^{-1}y - \overline{x}E(y - x)(Dy)(2\operatorname{Im}(y))^{-1}\right)f(y)$$

$$- \left(E(y - x)(Dy)(2\operatorname{Im}(y))^{-1}\overline{y} - \overline{x}E(y - x)(Dy)(2\operatorname{Im}(y))^{-1}\right)\mathcal{S}f(y)$$

$$= K_1(x, y)f(y) + K_2(x, y)\mathcal{S}f(y)$$

and the integral formula is proved.



Remark 2 The 3-forms K_1 , K_2 are real-analytic for $(x, y) \in \mathbb{H} \times (\mathbb{H} \setminus \mathbb{R})$ with $x \neq y$. If the closure of U does not intersect the real axis, then the two integrals with kernels K_1 and K_2 also converge separately and the integral formula (7) can be written as a sum of two integrals

$$f(x) = \int_{\partial U} K_1(x, y) f(y) + \int_{\partial U} K_2(x, y) \mathcal{S} f(y)$$
 for every $x \in U$.

The same also holds when the boundary ∂U is sufficiently smooth and the intersection $\partial U \cap \mathbb{R} \neq \emptyset$ is transversal.

Corollary 3 (Local Cauchy-type integral formula) *Let f be slice-regular on an axially symmetric open set* Ω . For any point $\tilde{x} \in \Omega$, there exists an axially symmetric open neighbourhood $W \subseteq \Omega$ of \tilde{x} such that for any bounded open set U with rectifiable boundary and $\overline{U} \subset W$, we have

$$f(x) = \int_{\partial U} \left(K_1(x, y) f(y) + K_2(x, y) \mathcal{S} f(y) \right) \tag{10}$$

for every $x \in U$.

Proof If $B \subseteq \Omega$ is an open ball centred at \tilde{x} , we can take W as the symmetric completion $\widetilde{B} = \bigcup_{x \in B} \mathbb{S}_x$ of B, where $\mathbb{S}_x = \alpha + \mathbb{S}\beta$ for $x = \alpha + J\beta \in B$. Then $W = \Omega_E$ with $E \subset \mathbb{C}$ having simply connected components (E is a complex disc, or a pair of disjoint conjugate discs, or the union of two intersecting conjugate discs). Since $f \in \mathcal{SR}(W)$, the corollary follows from Theorem 4.

The proof of the preceding corollary shows that the operator S can be defined on $SR(\Omega)$ for every axially symmetric slice domain $\Omega = \Omega_D$, without further assumptions on D. For every pair of slice-regular primitives $g \in SR(W)$, $\tilde{g} \in SR(\tilde{W})$ of f, we have $g'_s = \tilde{g}'_s$ on the intersection $W \cap \tilde{W}$. This common value defines Sf.

In the case of quaternionic polynomials, from the equality $S(x^n) = (n+1)^{-1} \widetilde{Z}_n$ we obtain a more explicit form of the integral formula:

Corollary 4 Let $f = \sum_{n=0}^{d} x^n a_n \in \mathbb{H}[x]$ be a polynomial. Then, for any bounded open set $U \subset \mathbb{H}$ with rectifiable boundary, we have

$$f(x) = \sum_{n=0}^{d} \int_{\partial U} \left(K_1(x, y) y^n + K_2(x, y) \frac{\widetilde{Z}_n(y)}{n+1} \right) a_n$$

for every $x \in U$.

Example 2 Let f(x) = x and let $B \subseteq \mathbb{H}$ be an open ball. Then $Sf(x) = \frac{1}{2}\widetilde{Z}_1(x) = x_0$. For every $x \in B$ we have

$$\int_{\partial B} (K_1(x, y)y + K_2(x, y)y_0) = \int_{\partial B} (K_1(x, y) + K_2(x, y))y_0 + \frac{1}{2} \int_{\partial B} K_1(x, y)(y - \overline{y})$$



$$\begin{split} &= \int_{\partial B} E(y-x)(Dy)y_0 + \frac{1}{2} \int_{\partial B} (E(y-x)(Dy)y - \overline{x}E(y-x)Dy) \\ &= \int_{\partial B} E(y-x)(Dy) \left(y_0 + \frac{1}{2}y\right) - \frac{\overline{x}}{2} \int_{\partial B} E(y-x)Dy = \left(x_0 + \frac{1}{2}x\right) - \frac{\overline{x}}{2} = x, \end{split}$$

since the function $g_1(x) = x_0 + \frac{1}{2}x$ and any constant function are Fueter-regular. Observe that if x is outside the closure of B the integral formula gives a zero value.

Remark 3 The integral formula (7) has an interpretation which is analogous to the classical Cauchy formula in complex analysis. If F is a complex holomorphic function on a neighbourhood W of \overline{D} , and G is a holomorphic primitive of F on W, then Cauchy's integral formula can be written as

$$F(x) = \int_{\partial D} dG_y(C(x, y)dy) \quad \text{for every } x \in D,$$

where $C(x, y) = (2\pi i)^{-1} (y - x)^{-1}$ is the Cauchy kernel and the real differential dG_y of G at y acts on a complex 1-form ady as multiplication by G'(y) = F(y).

If g is a slice-regular primitive of f on Ω , its real differential at $y \in \Omega \cap \mathbb{C}_I$ is the left \mathbb{C}_I -linear map given by

$$dg_{y} = R_{\frac{\partial g}{\partial x}(y)} \circ \pi_{I} + R_{g'_{s}(y)} \circ \pi_{I}^{\perp},$$

where $\pi_I: \mathbb{H} \to \mathbb{H}$ denotes the orthogonal projection onto the real vector subspace \mathbb{C}_I , $\pi_I^\perp = id_{\mathbb{H}} - \pi_I$ and R_a is the operator of right multiplication by $a \in \mathbb{H}$ (see [8, §3] and [16, Cor. 3.2]). Let $\widetilde{dg}_y: \mathbb{H}^2 \to \mathbb{H}$ be the left \mathbb{H} -linear extension of dg_y defined by

$$\widetilde{dg_y}(v, w) := R_{\frac{\partial g}{\partial x}(y)}(v) + R_{g_s'(y)}(w).$$

Then we have $dg_y(v) = \widetilde{dg_y}(\pi_I(v), \pi_I^{\perp}(v))$ for every $v \in T_y\Omega \simeq \mathbb{H}$. Since $\frac{\partial g}{\partial x}(y) = f(y)$ and $g_s'(y) = \mathcal{S}\{(y),$ the integral formula (7) of Theorem 4 can then be written as

$$f(x) = \int_{\partial U} \widetilde{dg_y}(K_1(x, y), K_2(x, y))$$
 for every $x \in U$,

where the action of the operator $\widetilde{dg_y}$ is extended linearly to quaternionic 3-forms by making it act on the coefficients of the forms.

We now deduce a local Cauchy-type integral formula for the slice derivatives of $f \in \mathcal{SR}(\Omega)$. Since

$$\frac{\partial^n f}{\partial x^n} = \frac{\partial^n f}{\partial x_0^n} \quad \text{for every } n \in \mathbb{N}$$



(see e.g. [11]), these formulas can be obtained by computing the derivatives of the kernels K_1 , K_2 w.r.t. x_0 . Let ∂_0 denote the partial derivative w.r.t. x_0 . Define $K_1^{(n)}(x, y) := \partial_0^n K_1(x, y)$ and $K_2^{(n)}(x, y) := \partial_0^n K_2(x, y)$.

Proposition 3 We have

$$\partial_0^n E(y - x) = \frac{n!}{2\pi^2} \mathcal{P}_{-n-3}(y - x),\tag{11}$$

and

$$K_{1}^{(n)}(x,y) = \frac{n!}{2\pi^{2}} \mathcal{P}_{-n-3}(y-x)(Dy)y(y-\overline{y})^{-1}$$

$$-\frac{n!}{2\pi^{2}} (\mathcal{P}_{-n-2}(y-x) + \overline{x}\mathcal{P}_{-n-3}(y-x)) Dy(y-\overline{y})^{-1}, \qquad (12)$$

$$K_{2}^{(n)}(x,y) = \frac{n!}{2\pi^{2}} (\mathcal{P}_{-n-2}(y-x) + \overline{x}\mathcal{P}_{-n-3}(y-x)) Dy(y-\overline{y})^{-1}$$

$$-\frac{n!}{2\pi^{2}} \mathcal{P}_{-n-3}(y-x)(Dy)\overline{y}(y-\overline{y})^{-1}. \qquad (13)$$

for every $n \in \mathbb{N}$. In particular,

$$K_1^{(n)}(x, y) + K_2^{(n)}(x, y) = \frac{n!}{2\pi^2} \mathcal{P}_{-n-3}(y - x) Dy = \partial_0^n E(y - x) Dy.$$

Proof Since E is axially monogenic, we have

$$\partial_0 E = (\partial + \overline{\partial}) E = \partial E = \frac{1}{2\pi^2} \partial \mathcal{P}_{-3}.$$

Since $\partial \mathcal{P}_n = (n+2)\mathcal{P}_{n-1}$ for every $n \in \mathbb{Z}$ (see [20, Rem. 27]), we get

$$\partial_0 E = -\frac{1}{2\pi^2} \mathcal{P}_{-4}$$

and then, inductively,

$$\partial_0^n E(x) = (-1)^n \frac{n!}{2\pi^2} \mathcal{P}_{-n-3}(x)$$
 for every $n \in \mathbb{N}$.

Formula (11) follows immediately. In order to obtain (12) and (13), we must also compute $\partial_0^n(\overline{x}E(y-x))$. From

$$\partial_0(\overline{x}E(y-x)) = E(y-x) + \overline{x}\,\partial_0E(y-x)$$

we get inductively

$$\partial_0^n(\overline{x}E(y-x)) = n\partial_0^{n-1}E(y-x) + \overline{x}\partial_0^n E(y-x).$$



Using (11) we obtain

$$\partial_0^n(\overline{x}E(y-x)) = \frac{n!}{2\pi^2} \left(\mathcal{P}_{-n-2}(y-x) + \overline{x} \, \mathcal{P}_{-n-3}(y-x) \right).$$

From this equality and (11), we get (12) and (13).

Corollary 5 (Local Cauchy-type formula for slice derivatives) Let $f \in SR(\Omega)$. For any point $\tilde{x} \in \Omega$, there exists an axially symmetric open neighbourhood $W \subseteq \Omega$ of \tilde{x} such that for any bounded open set U with rectifiable boundary and $\overline{U} \subset W$, we have

$$\frac{\partial^{n} f}{\partial x^{n}}(x) = \int_{\partial U} \left(K_{1}^{(n)}(x, y) f(y) + K_{2}^{(n)}(x, y) \mathcal{S} f(y) \right) \tag{14}$$

for every $x \in U$, $n \in \mathbb{N}$.

Example 3 Let f and $B \subseteq \mathbb{H}$ be as in Example 2. For every $x \in B$ we have

$$\begin{split} &\int_{\partial B} \left(K_{1}^{(1)}(x,y)y + K_{2}^{(1)}(x,y)y_{0} \right) \\ &= \int_{\partial B} (K_{1}^{(1)}(x,y) + K_{2}^{(1)}(x,y))y_{0} + \frac{1}{2} \int_{\partial B} K_{1}^{(1)}(x,y)(y - \overline{y}) \\ &= \int_{\partial B} \partial_{0}E(y - x)(Dy)y_{0} + \frac{1}{2} \int_{\partial B} (\partial_{0}E(y - x)(Dy)y - E(y - x)Dy) \\ &- \frac{1}{2} \int_{\partial B} \overline{x} \partial_{0}E(y - x)Dy \\ &= \int_{\partial B} \partial_{0}E(y - x)(Dy)(y_{0} + \frac{1}{2}y) - \frac{1}{2} \int_{\partial B} E(y - x)Dy - \frac{\overline{x}}{2} \int_{\partial B} \partial_{0}E(y - x)Dy \\ &= \frac{3}{2} - \frac{1}{2} = 1 = \frac{\partial f}{\partial x}, \end{split}$$

since the function $x_0 + \frac{1}{2}x$ is Fueter-regular with derivative 3/2 w.r.t. x_0 .

Remark 4 One could deduce Cauchy-type estimates for the slice derivatives of a slice-regular function from formula (14). However, we observe that they were already obtained more easily by means of the two-dimensional Cauchy formula (see [9, Prop. 6.8])

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